

Research and Design of Embedded System for Emissivity Measurement

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Abstract

As an ion generating device, the ion source is widely used in accelerator, space environment and space physics, integrated circuit manufacturing, wafer production, medical and other fields. Emissivity is an important index to indicate the quality of ion source beam. An emittance measurement system for low-energy and high-current ion beams based on the principle of multi-slit single wire measurement was designed and developed. The system includes a step motor, a beam detector (Faraday cup), a weak signal amplifier, isolators and filters, a C8051F500 microcontroller, and a RS-232 interface circuit. Compared with the existing emittance measurement equipment, the system has the advantages of versatility, portability and high cost performance.

Keywords: Ion source, Emissivity, Measurement, Multi-slit single wire measurement

1. Introduction

As an ion generating device, ion source is widely used in accelerator, space environment and space physics, integrated circuit manufacturing, wafer production, medical and other fields^[1-4]. For example, in an accelerator, in order to increase the velocity or kinetic energy of charged particles, an ion source is needed to produce charged particles at first. Charged particles can be accelerated only when they are sent to the accelerator by ion beam extraction equipment. The effect of acceleration depends on the quality of the beam produced by the ion source. The beam quality depends on its emittance, brightness and energy divergence, and the most commonly used is the beam emittance value. If the emittance value is large, the particles swarm will disperse, the beam will not transmit well, and the acceleration effect will become worse. If the emittance value is small, the particles swarm will be concentrated, which will not only facilitate the beam transmission, but also produce a good beam acceleration effect, and the accelerator performance will be better. Therefore, the more precise the emittance value is, the better the performance of the accelerator will be, the si-

mpler the design of the accelerator will be, and the easier the study of the beam will be^[5].

There are mainly two kinds of emittance measurement methods, namely, interception measurement method and non-interception measurement method. In 1983, R.H. Miller et al. proposed that the transverse emittance of a beam can be measured by a beam position detector without interception^[6]. Later, many researchers began to adopt this method. For example, in 1998, researchers in the LANL Laboratory in the United States used this method to measure transverse emissivity for the first time^[7]. Jansson et al. proposed the method of emissivity measurement by using magnetic quadrupole extractor which is another non-interception measurement method^[8]. In 2007, the researchers in the European Center for Nuclear Research (CERN) used a laser line scanner to precisely measure the beam emittance of the beam transport system of the International Linear Collider (ILC)^[9]. Wang et al. measured the beam emittance by changing the focus intensity for several times^[10]. Xu et al. used a digital camera to capture the envelope of the beam and change the focus intensity to measure the emittance^[11].

Songet al. studied the measurement of beam emittance by the CT (Computed Tomography) method^[12]. Masoumza dehet al. used CST Studio code to study and design the Faraday cups because they are widely used to characterize ion beam current^[13]. Kazemi et al. simulated the extraction of the proton beam from the duoplasmatron ion source with Computer Simulation Technology (CST) software through its particle tracking module^[14]. Li et al. developed an emittance measurement system based on EPICS software system, to measure beam emittance of ECR ion source more accurately and reliably^[15]. Ebrahimiasabiet al. described the design and construction of a Multi Array Faraday Cup for both beam profiling and current measurements in a Penning ion source, and then designed a testing set-up to test and calibrate the system^[16]. The main methods of emittance measurement adopted in accelerators and their respective characteristics are listed in Table 1.

For the measurement of emittance of high-current ion beam, the pepper screen method, three-gradient method and three-section method are all no longer applicable because of some special properties of high-current ion beam. Although the CT method has the advantages of high measurement accuracy and it is not needed to preset the initial beam emittance, its technology is not yet mature. Therefore, the slit wire method is still the most important measurement emittance method of high current ion beam. In this paper, we designed and developed an emittance measuring instrument for low energy and high current ion beams based on multi-slits single wire method.

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Table 1. Main Methods of Emittance Measurement adopted in Accelerators

Sr. No	Methods	Characteristics
1	Pepper screen/slit-wire method	Interception, low Energy, relieving Space Charge.
2	Magnetic scanning, narrow slit and fluorescent screen	Interception, low Energy, the emittance increases, when energy divergence exists.
3	Cherenkov radiation "dual imaging"	Interception, no need to assume no hypothesis of beam distribution.
4	Single hole sampling	Interception, high current, high pulse momentum, small section.
5	Double screen method	Interception, beam waist positioning
6	Three section (gradient) method	Interception, inclusion of space charge force, hypothesis of ideal ellipse.
7	Six section (gradient) method	Non-interception, high energy, no hypothesis of beam distribution, measure x, y direction emittance simultaneously.

2. Measurement Principle of Multi-slit Single Wire Method

The direction of the beam is set as y axis and the scanning direction of Faraday cup is x axis. The measurement principle of multi-slits single wire method is shown in Fig. 1. Assuming that the beam flow is divided into p unit beams (the number of slits). The Faraday cup scans in a plane with a distance of L behind the sample. x is the plane coordinate of the slit, θ is the divergence angle, and X is the plane coordinate of the Faraday cup. The root mean square (RMS) of emittance can be calculated according to Eq. (1).

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$$\varepsilon_x^2 = \frac{1}{N^2} \left\{ \left[\sum_{j=1}^p n_j (x_{sj} - \bar{x})^2 \right] \cdot \left[\sum_{j=1}^p \left[n_j \sigma_{x'j}^2 + n_j (\bar{x}'_j - \bar{x}') \right] \right] - \left[\sum_{j=1}^p n_j x_{sj} \bar{x}'_j - N \bar{x} \bar{x}' \right]^2 \right\} \quad (1)$$

where, ε_x^2 is the root mean square of emittance, $N = \sum_{j=1}^p n_j$. Then the normalized root mean square of beam emittance can be calculated as Eq.(2).

$$\varepsilon_{xn} = \beta \gamma \varepsilon_n \quad (2)$$

where, β is the relativistic velocity of particles, and $\gamma = (1 - \beta^2)^{-1/2}$.

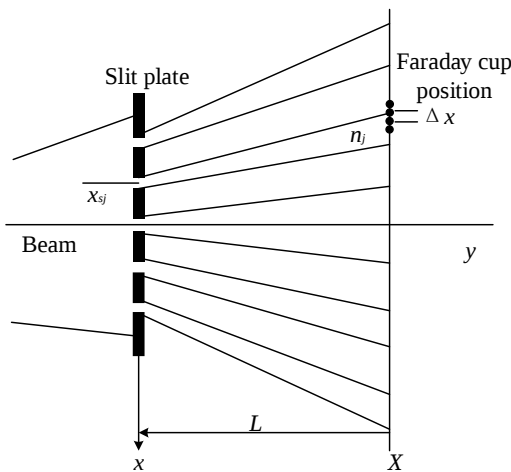


Fig.1.Principle Diagram for Emissivity Measurement of Multi-slit Single Wire

3.System Architecture

We designed and developed an emittance measuring instrument based on the above measurement principle. The system structure is shown in Fig.2, and it includes a

step motor, a beam detector (Faraday cup), a weak signal amplifier, isolators and filters, a C8051F500 microcontroller, and an RS-232 interface circuit.

3.1.Beam Detector

The beam detector (Faraday cup) is responsible for converting the beam intensity information into electrical signals. The Faraday cup is controlled by the step motor to move radially.

3.2.Weak Signal Amplifier

This signal produced by the beam detector is very weak and cannot meet the requirements of A/D conversion, so a weak signal amplifier circuit is needed. The converted small voltage signal ranges from 10 to 50 mV, while the sampling voltage range of ADC is 0 to 5 V, so the detection circuit amplifies the signal more than 100 times. Two stages of amplification are set up here. The first stage amplifier uses a high-precision instrument amplifier INA111. In the second stage amplifier, the program-controlled amplifier MAX4132 is selected, by considering that the measurement range and accuracy of beam intensity are contradictory. Seven amplification ranges are set up, so that the amplification circuit can automatically select the appropriate range according to the intensity of the beam, and realize the wider range and high precision measurement of the beam. The weak signal amplifier was designed as Fig.3.

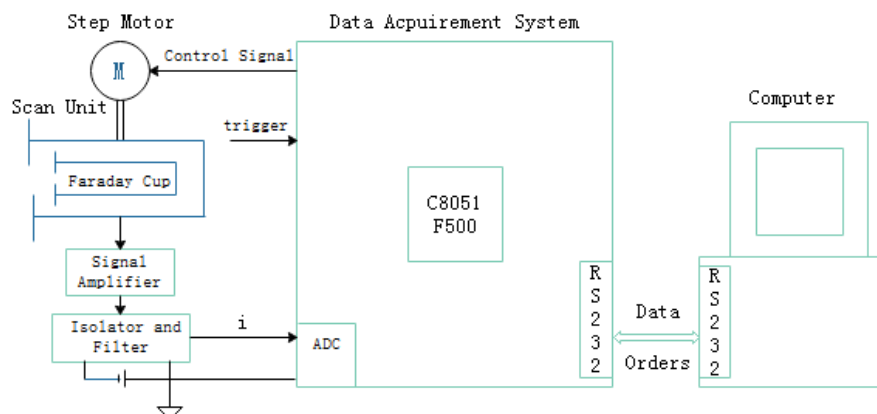


Fig.2.System Structure Diagram

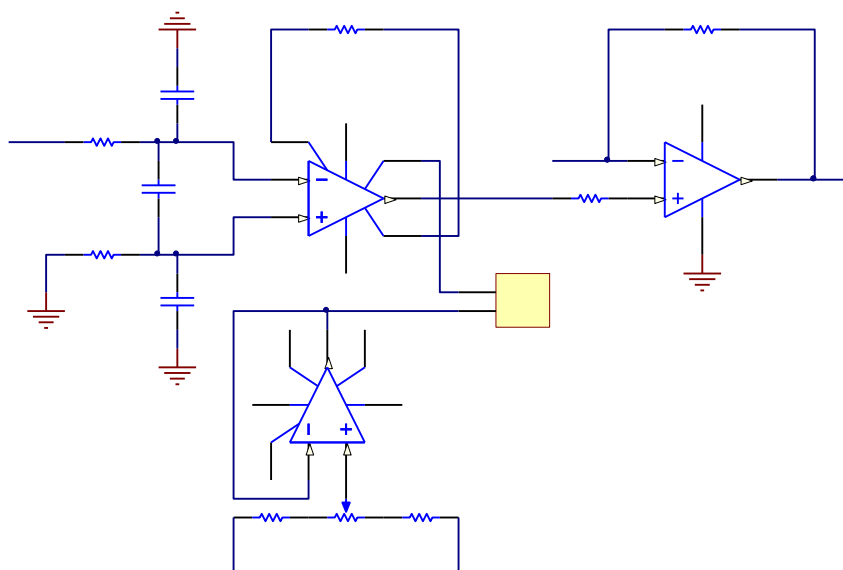


Fig.3.WeakSignalAmplifier

3.3.Signal Isolator and Filter

Because the interference at 50Hz can easily enter the measurement system, a 50Hz notch filter is built by using an active filter UAF42. In addition, in order to completely isolate the analog circuit from the microcontroller circuit electrically to reduce the interference, a photocoupler isolation circuit is added at the end of the conditioning circuit. In order to maximize the bandwidth of the system, a high linearity optocoupler HCNR201 is selected. The isolation circuit is shown in Fig. 4.

3.4.C8051F500 Microcontroller

The C8051F500 microcontroller is the core of the system, and its main functions are as follows:

(1) Signal acquisition. The output signal of operational amplifier MAX4132 is converted to A/D after filtering and

isolating circuit. It is not difficult to realize the A/D conversion, because the C8051F500 microprocessor has ADC converters.

(2) Control of the stepper motor. A timer in the C8051F500 microcontroller is used to generate a control signal, and an I/O pin of the microcontroller is selected to output the control signal to control the rotation of the stepper motor.

Realize the communication with PC. The transmission of control command and data between the system and PC is realized by RS-232 serial port. In order to realize the anti-interference isolation of the input and output of the system, a digital isolator ADUM1402 is used to isolate the signal lines TXD0 and RXD0 of the controller.

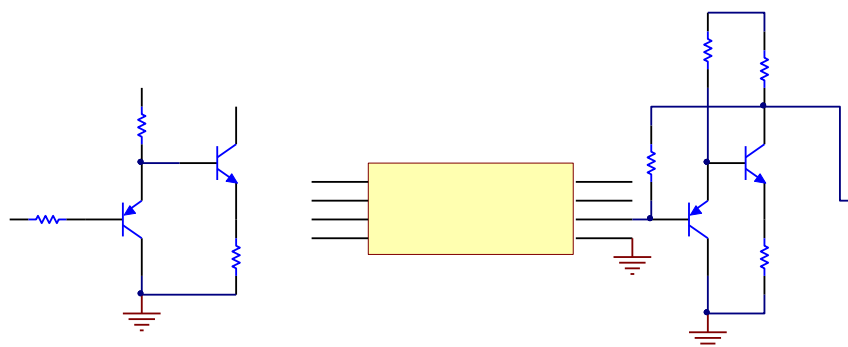


Fig.4.IsolationCircuit

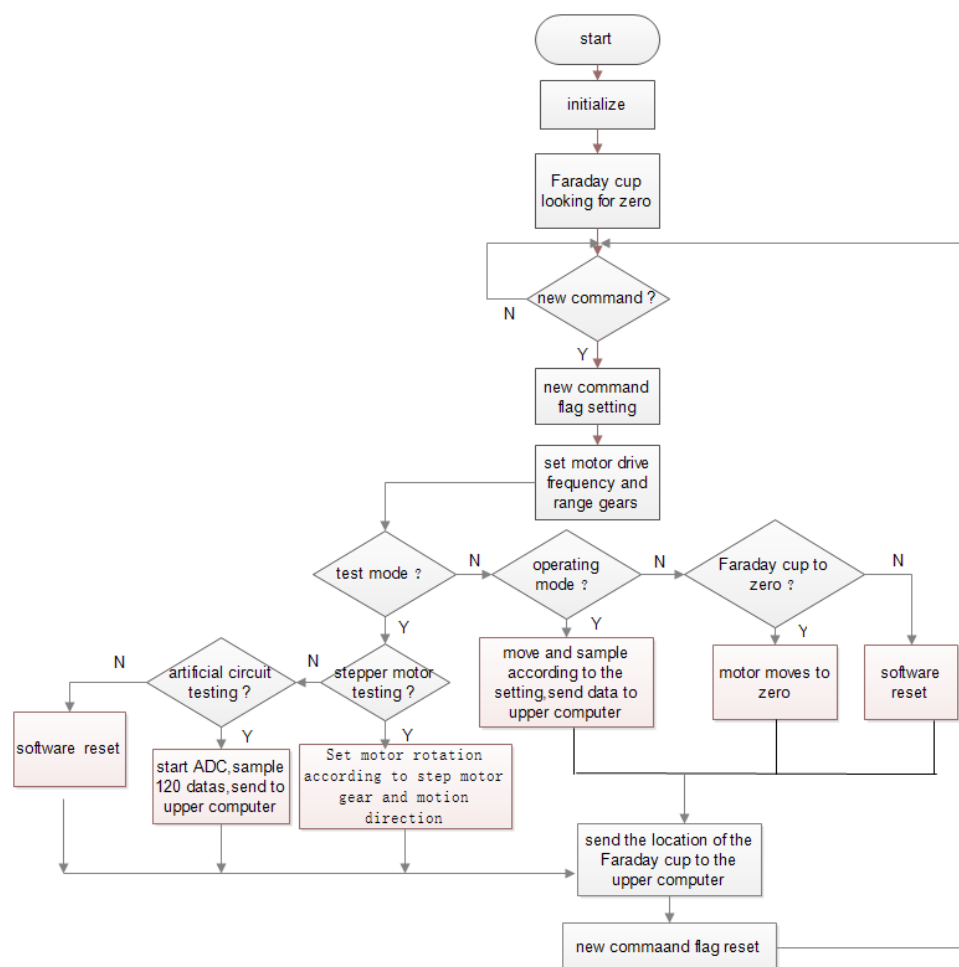


Fig.5.Main Program Flow of the System

4. System Software Design

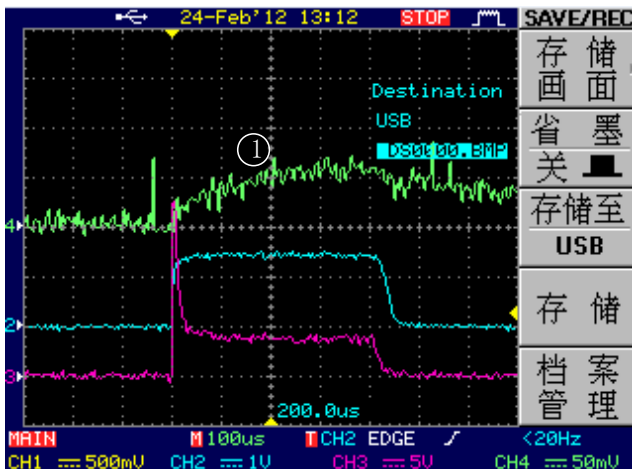
After initialization, the system receives the command signals sent by PC circularly by the serial port interrupt. The received command signal is judged by the frame head and the frame end at first, in order to ensure the correctness of the command. If there is an error, the command will be received again; if there is no error, the command will be parsed. Then, according to the command type, the corresponding set up operation is performed. At the same time, the voltage data sampled by ADC is sent to PC. Finally, the measurement and control functions are completed. The main program flow is shown in Fig.5.

In addition to the system software, some software programming is needed in PC. The main functions of PC are as follows: (1) realize the processing and displaying of system status information and measurement results; (2) send control commands to the measurements system. The corresponding software was developed with Microsoft Visual C++

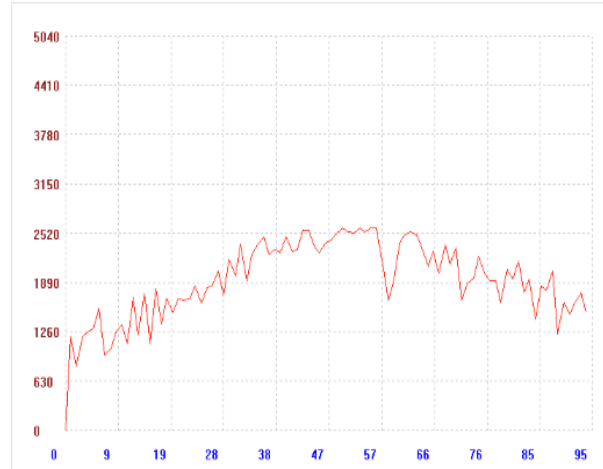
+6.0. Then the normalized RMS emittance value and emittance measurement image are obtained by clicking the "Calculate emittance" button on the software interface. The detailed software design process in PC is no longer introduced.

5. Result and Analysis

The emittance of the electron cyclotron resonance (ECR) ion source is measured by the designed system. Firstly, single point measurement is carried out. When the Faraday cup moves to the position of one unit beam, it stops and repeats the measurement of the beam at the position of the beam. This kind of measurement is called single point measurement. The measurement results are shown in Fig.6. In Fig. 6(a), line (1) (green) is the unit beam curve measured by oscilloscope, while in Fig. 6(b), the measurement results of the designed system are shown.



(a) Measurement Results of Oscilloscope



(b) Measurement Results of the Designed System

Fig.6. Single Point Measurement Results

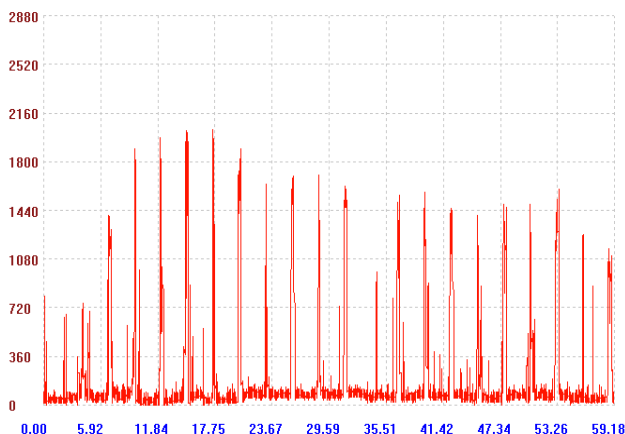


Fig.7. Measurement Results

Then, all the beam pulses are recorded by adjusting the amplifying frequency and scanning speed. The measurement results are shown in Fig.7. It is easy to see that there are some small burrs, small peaks and even big peaks at the bottom of the measuring curve, which are the background noise of the system. Although some noises are relatively large and form peaks, they mostly exist in the form of pulses, which are distinct from the slow climbing of the main peak. Most of the small peaks are uneven, but the bottom of the measurement curve is generally flat, so the influence of background noise can be minimized in the subsequent capacitance calculation process. The output

current of Faraday cup ranges from 0 to 2000 nA, and the measurement accuracy is 2% to 8%.

6. Conclusions

Based on the principle of multi-slits single-wire measurement, an emittance measurements system is designed and developed in this paper. Aiming at the problems of high voltage pulsed discharge, complex grounding and electromagnetic interference in the measurement environment, a series of anti-interference measures such as isolation, filtering, shielding and single-point grounding are adopted to ensure the reliability of the system. The test results show that the system has high measurement accuracy and can meet the requirements of general users.

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